

# HGM9560 BUS TIE MAINS PARALLEL UNIT USER MANUAL



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### **Table 1 Version History**

Date	Version	Note	
2013-12-30	1.0	Original release.	
		1. Add descriptions of mains trip function;	
2024-01-03	1.1	2. Modify the parameter contents of user manual to be the	
		same with controller.	
		1. Add mains over current 1/2, stop mode MB control and	
2024 11 05	1.2	maintenance settings;	
2024-11-05		2. Add mains switch control unavailable and mains switch	
		control unavailable feedback for input items.	
2025-02-13	1.3	Modify the working and storage temperature ranges.	



This manual is suitable for HGM9560 bus tie mains parallel unit only.

### **Table 2 Clarification of Notation**

Sigh	Instruction
NOTE	Highlights an essential element of a procedure to ensure correctness.
CAUTION!	Indicates a procedure or practice, which, if not strictly observed, could result in damage or destruction of equipment.
WARNING!	Indicates a procedure or practice, which could result in injury to personnel or loss of life if not followed correctly.



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#### 1 OVERVIEW

**HGM9560** Bus Tie Mains Parallel Unit is designed for manual/auto parallel system which composed by gensets and one-way/multi-way mains. It allows automatic start/stop and parallel running function. It fit with LCD display, graphic display, optional Chinese, English and other languages interface, and it is reliable and easy to use.

**HGM9560** Bus Tie Mains Parallel Unit has multiple running states when it is parallel with mains: Genset output fixed active power and fixed reactive power; Mains peak lopping; Provide fixed power to mains; Load takeover; No-break return to mains supply.

The powerful 32-bit Microprocessor contained within the unit allows for precision parameters measuring, fixed value adjustment, time setting and set value adjusting and etc.. Majority parameters can be configured from front panel, and all parameters can be configured by USB interface (or RS485) to adjust via PC. It can be widely used in all types of automatic genset parallel system with compact structure, simple connections and high reliability.

### 2 PERFORMANCE AND CHARACTERISTICS

- With ARM-based 32-bit SCM, high integration of hardware and more reliable;
- → 480x272 TFT LCD with backlight, multilingual interface (including English, Chinese or other languages)
  which can be chosen at the site, making commissioning convenient for factory personnel;
- Improved TFT LCD wear-resistance and scratch resistance due to hard screen acrylic;
- Silicon panel and pushbuttons for better operation in high/low temperature environment;
- RS485 communication port enables remote control, remote measuring, remote communication via ModBus protocol.
- Suitable for 3-phase 4-wire, 3-phase 3-wire, single phase 2-wire, and 2-phase 3-wire systems with voltage 120/240V and frequency 50/60Hz;
- Collects and shows 3-phase voltage, current, power parameter and frequency of Bus/mains.

Mains Bus

Line voltage (Uab, Ubc, and Uca)

Line voltage (Uab, Ubc, and Uca)

Phase voltage (Ua, Ub, and Uc)

Phase voltage (Ua, Ub, and Uc)

Phase sequence Phase sequence

Frequency (Hz) Frequency (Hz)

Current IA, IB, IC Current IM

Each phase and total active power kW Active power kW

Each phase and total reactive power kvar Reactive power kvar

Each phase and total apparent power kVA Apparent power kVA

Each phase and average power factor PF Power factor PF

Accumulate total gen power kWh, kvarh, kVAh

Rate of Change of Frequency ROCOF

Vector Shift VS

Earth current IE

Negative Sequence Current INB

- Perfect mains split protection: over/under frequency, over/under voltage, ROCOF and vector shift;
- Synchronization parameters: Voltage Difference Between Bus and Mains, Frequency Difference Between Bus and Mains, Phase Difference Between Bus and mains;
- Multiple running modes in auto state: AMF (Automatic Mains Failure), Island Mode, Fixed Power Output/Input, Peak Lopping Mode and Load Takeover Mode;
- Ramp on and ramp off function;
- Control and Protection: automatic start/stop of the gen-set, ATS (Auto Transfer Switch) control with perfect fault indication and protection function;

- All output ports are relay output;
- Parameter setting: parameters can be modified and stored in internal EEPROM memory and cannot be lost even in case of power outage; most of them can be adjusted using front panel of the controller and all of them can be modified using PC via USB or RS485 ports;
- ➤ Widely power supply range DC(8~35)V, suitable to different starting battery voltage environment;
- Event log, real-time clock, scheduled start & stop generator (can be set as start genset once a day/week/month whether with load or not);
- Accumulative total electric energy A and B. Users can reset it as 0 and re-accumulative the value which make convenience to users to count the total value as their wish.
- With maintenance function. Actions (warning, trip and stop, shutdown) can be set when maintenance time out;
- All parameters used digital adjustment, instead of conventional analog modulation with normal potentiometer, more reliability and stability;
- ▶ IP55 waterproofness level can be achieved with the help of rubber-ring gasket between shell and control panel.
- Metal fixing clips enable perfect in high temperature environment;
- Modular design, self extinguishing ABS plastic shell, pluggable terminal, built-in mounting, compact structure with easy installation;



### 3 SPECIFICATION

**Table 3 Performance Parameters** 

Parameter	Details	
	DC8V ~ DC35V, DC reverse protection	
	Resolution: 0.1V	
Marking Valtage Dongs	Accuracy:1%	
Working Voltage Range	DC12V ~DC30V, DC reverse protection (UL Certification)	
	Resolution: 0.1V	
	Accuracy:1%	
Overall Consumption	<4W (Standby mode: ≤2W)	
AC Input:		
3 Phase 4 Wire	AC15V - AC360V (ph-N)	
3 Phase 3 Wire	AC30V - AC620V (ph- ph)	
Single Phase 2 Wire	AC15V - AC360V (ph-N)	
2 Phase 3 Wire	AC15V - AC360V (ph-N)	
Alternator Frequency	50Hz/60Hz	
Flexible Relay Output 1	7A DC28V power supply output	
Flexible Relay Output 2	7A DC28V power supply output	
Flexible Relay Output 3	7A DC28V power supply output	
Flexible Relay Output 4	7A AC250V volts free output	
Flexible Relay Output 5	7A AC250V volts free output	
Flexible Relay Output 6	7A AC250V volts free output	
Flexible Relay Output 7	16A DC28V power supply output	
Flexible Relay Output 8	16A DC28V power supply output	
Digital Input 1~7	Low limit voltage is 1.2V, high limit voltage is 60V.	
CT Secondary Current	Rated: 5A	
RS485	Isolated, half-duplex, 9600 baud rate,	
R5465	max. communication length 1000m	
MSC CAN	Isolated, max. communication length 250m,	
MSC CAN	using Belden 9841 cable or equivalent.	
	5Hz~8Hz: ±7.5mm	
Vibration	8Hz~500Hz: 2g	
	IEC 60068-2-6	
	50gn, 11ms, half-sine, three consecutive shocks are applied in each of the	
Shock	three mutually perpendicular directions, i.e. a total of 18 times.	
	IEC 60068-2-27	
ъ т.	20g <sub>n</sub> , 16ms, half-sine	
Bump Test	IEC 60255-21-2	
	According to EN 61010-1 installation category (over voltage category) III,	
Safety Requirement	300V, pollution class 2, altitude 3000m	
Case Dimensions	266mm x 182mm x 45mm	
Panel Cutout	214mm x 160mm	
Working Temperature:	(-40~+70)°C	
Working Humidity	(20~93)%RH	
Storage Temperature:	(-40~+80)°C	
. g . p	IP55 Gasket	

Parameter	Details	
	Apply AC2.2kV voltage between high voltage terminal and low voltage	
Insulation Intensity	terminal;	
	The leakage current is not more than 3mA within 1min.	
Due doest Occupility of	GB/T 37089 Reciprocating internal combustion engine driven alternating	
Product Compliance	current generating sets—Controller	
Weight	0.95kg	

### 4 OPERATION

#### 4.1 INDICATOR LIGHT



Fig.1 HGM9560 Front Panel

NOTE: Selected light indicators description.

**Table 4 Warning indicator and Alarm indicator** 

Alarm Type	Warning Indicator	Alarm Indicator
Warning	Slow flashing	Slow flashing
Trip Alarm	Slow flashing	Slow flashing
Shutdown Alarm	Off	Fast flashing
Trip and Stop Alarm	Off	Fast flashing

Running indicator: illuminated from crank disconnect to ETS while off during other periods.

Bus normal light: It is light on when bus is normal; flashing when bus state is abnormal; off when there is no bus power.

Mains normal indicator: It is illuminated when mains is normal; flashing when mains state is abnormal; off when there is no mains power.



### **4.2 PUSHBUTTONS**

**Table 5 Keys Functions** 

Icon	Function	Description	
Stop O	Stop	When the controller is in Auto/Manual mode, press this button will stop the system generators (if the generators are in Auto mode).  Reset alarm in stop mode;  Lamp test (press at least 3 seconds);	
Start	Start	When the controller is in Manual mode, press this button will start the system generators (if the generators are in Auto mode).	
Manual	Manual Mode	Press this key and controller enters in <b>Manual</b> mode.	
Auto	Auto Mode	Press this key and controller enters in <b>Auto</b> mode.	
Alarm Mute	Mute/Reset Alarm	Alarming sound off; If trip alarm occurs, pressing the button at least 3 seconds can reset this alarm.	
Open Close	Bus Close/Open	Can control bus to switch on or off in <b>Manual</b> mode.	
Open Close	Mains Close/Open	Can control mains to switch on or off in <b>Manual</b> mode.	
	Up/Increase	Screen scroll;     Up cursor and increase value in setting menu.	
	Down/Decrease	Screen scroll;     Down cursor and decrease value in setting menu.	
	Left	1) Screen scroll; 2) Left move cursor in setting menu.	
	Right	1) Screen scroll; 2) Right move cursor in setting menu.	
Enter	Set/Confirm	<ol> <li>Pressing and holding for more than 3 seconds enters parameter setting menu;</li> <li>In settings menu confirms the set value.</li> </ol>	
Esc	Exit	1)Return to main menu; 2) Return to previous menu in setting menu.	

**WARNING:** Default password is 00318, user can change it in case of others change the advanced parameters setting. Please clearly remember the password after changing. If you forget it, please contact Smartgen services and send all PD information in the controller page of "**ABOUT**" to us.



#### 4.3 LCD DISPLAY

#### 4.3.1 MAIN DISPLAY

Main screen show pages; use to scroll the pages and to scroll the screen.

**★Main Screen**, including as below,

Mains: voltage, frequency, current, active power, reactive power

Bus: voltage, frequency, active power, reactive power

Some status

**★Status**, including as below,

Module status, mains status, ATS status

**★Bus**, including as below,

Phase voltage, line voltage, frequency, phase sequence, multi-genset total power

**NOTE**: If load current transformer is enabled, this page also includes: current, active power, reactive power, apparent power, power factor.

**★Mains**, including as below,

Phase voltage, line voltage, frequency, phase sequence, current, active power(positive and negative), total active power (positive and negative), reactive power(positive and negative), total reactive power (positive and negative), apparent power, total apparent power, power factor(positive and negative), average power factor (positive and negative), accumulated energy (kWh, kVarh, kVAh), earth current, negative sequence current, ROCOF (rate of change of frequency), VS (vector shift).

**★SNYC**, including as below,

Voltage difference, frequency difference, angle difference, Bus active power percentage, Bus target active power percentage, Bus reactive power percentage, Bus target reactive power percentage, MSC status

#### **★Alarm**

Display all alarm information (warning alarm, shutdown alarm, trip and stop alarm, trip alarm, mains trip).

#### **★Event log**

Make records about all start/stop events (shutdown alarm, trip and stop alarm, manual /auto start or stop) and the real time when alarm occurs.

**★Others**, including,

Time and Date, maintenance due, input/output ports status.

**★About,** including,

Issue time of software and hardware version, product PD number.

### 4.3.2 USER MENU AND PARAMETERS SETTING MENU



key for more than 3s to enter into user manual.

**★**Parameter

After entering the correct password (factory default password is 00318) you can enter parameter settings screen.

**★**Language

Selectable Chinese, English and others (default: Espanol)

**★**Clear users' accumulation

Can clear total electric energy A and B.

Parameter setting including as following,

- **★**Mains setting
- **★**Timer settings
- **★**Battery setting
- **★**Bus settings
- **★**Breaker settings
- **★**Input port settings
- **★**Output port settings
- **★**Module settings
- ★Scheduled Run Settings
- ★Scheduled Not Run Settings
- **★**Maintenance settings
- **★**Synchronization settings

### Example:

Return	>Start Delay	Form1: Use 🗪 🔝 to scroll settings,
Mains setting	>Stop Delay	to enter settings (form 2), (Esc) to exit
Timers setting >		to enter settings (form 2), to exit
Battery setting		settings menu.
Bus setting		
Breaker setting		
Input setting		
Output setting		
Module setting		
Scheduled Run Setting		
Scheduled Not Run Setting		
Maintenance		
Synchronization setting		

Return	>Start Delay	Form 2: Use to scroll settings,
Mains setting	>Stop Delay	to enter settings (form 4), Esc to
Timers setting >		to enter settings (form 4), of to
Battery setting		return to previous menu. (form 1)
Bus setting		
Breaker setting		
Input setting		
Output setting		
Module setting		
Scheduled Run Setting		
Scheduled Not Run Setting		
Maintenance		
Synchronization setting		

Return	>Start Delay	Form 3: Use to scroll settings,
Mains setting	>Stop Delay	to confirm settings (form 4), Esc to
Timers setting >		to confirm settings (form 4), $\bigcirc$ to
Battery setting		return to previous menu. (form 1)
Bus setting		
Breaker setting		
Input setting		
Output setting		
Module setting		
Scheduled Run Setting		
Scheduled Not Run Setting		
Maintenance		
Synchronization setting		
> Start Delay		Enter
> Stop Delay	00008	Form 4: Press to enter settings

> Stop Delay	00008	Form 4: Press to enter settings
		(form 5), (Esc) to return to previous menu. (form 6).
> Start Delay	_	Form 5: Press <b>1</b> to change cursor
> Stop Delay	00008	position, are used for changing
		cursor value, to confirm setting (form
		4), Esc to exit setting (form 4).

> Start Delay		Form 6: Use to scroll settings.
> Stop Delay	80000	to enter settings (form 4), Esc to
		return to previous menu. (form 1).

NOTE: Pressing



can exit setting directly during setting.

### 4.4 AUTO START/STOP OPERATION

Auto mode is selected by pressing the button; a LED besides the button will illuminate to confirm the operation.

#### Automatic Start Sequence:

- When remote start (on-load) input is active or mains is abnormal, "Start Delay" timer is initiated; "Start Delay" countdown will be displayed on LCD;
- When start delay is over, the controller will issue a start command, "Start Request XXs" information will be displayed on LCD;
- Any available 9560 in auto mode will be issued with a start signal. Please refer to the 9510 operating manual for further details of the start sequence.
- 4. Once the Minimum number of sets have synchronized onto the bus, the 9560 will enter into normal running:
- a) If mains switch didn't close, then bus close relay activate.
- b) If mains switch already closed, the controller will adjust speed and voltage to synchronize bus with mains; when synchronism requirements has been achieved, bus close signal will be initiated and the bus will be paralleled with the mains. Once the bus has synchronized to the mains, the power will be ramped off the bus.
- 5. If the number of the synchronized set is less than the Minimum number after the "Start Request" delay is over, then the "Too Few Modules" alarm will be initiated.

Note: When started via "Remote Start (off Load)" input, same procedures as above but bus close relay deactivated, moreover, bus off load. When started via "Remote Start (Demand)" input, same procedures as above if the start requirements has been achieved (e.g. when the load has exceed the set value in shave lopping mode).

### **Automatic Stop Sequence,**

- 1) When the "Remote Start" signal is removed, and moreover, mains is normal, the Stop Delay is initiated.
- 2) Once this "stop delay" has expired,
- a) If mains switch didn't close, then bus open relay activate.
- b) If mains switch already closed, first of all, the controller will transfer load to mains, and only then bus open relay activate.

- 3) The controller will issue a stop command and the genset is in "At Rest" mode.
- 4) Any available 9560 in auto mode will be issued with a stop signal. Please refer to the 9510 operating manual for further details of the stop sequence.

#### 4.5 MANUAL START/STOP OPERATION

Manual mode is selected by pressing the button; a LED besides the button will illuminate to confirm the operation.

#### **Manual Start Operation:**

- 1. Press button to start the genset, the controller will issue a start command, "Start Request XXs" information will be displayed on LCD;
- 2. Any available 9560 in auto mode will be issued with a start signal. Please refer to the 9510 operating manual for further details of the start sequence.
- 3. Once the Minimum number of sets have synchronized onto the bus, the 9560 will enter into normal running:
- 4. If the number of the synchronized set is less than the Minimum number after the "Start Request" delay is over, then the "Too Few Modules" alarm will be initiated.

#### **Manual Transfer Procedures**

Bus Close Operation: During genset is normal running, press Bus Close Button



- 1) If mains switch didn't close, then bus close relay activate.
- 2) If mains switch already closed, the controller will adjust speed and voltage to synchronize bus with mains; when synchronism requirements have been achieved, bus close signal will be initiated and the bus will be paralleled with the mains. Once the bus has synchronized to the mains, the power will be ramped off the mains.

### **Bus Open Operation:** Press Bus Open Button



- 1) If mains switch didn't close, then bus open relay activate.
- If mains switch already closed, first of all, the controller will transfer load to mains, and only then bus open relay activate.

Mains Close Operation: During mains is in normal status, press Mains Close Button



- 1) If bus switch didn't close, then mains close relay activates.
- 2) If bus switch already closed, the controller will adjust speed and voltage to synchronize bus with mains; when synchronism requirements has been achieved, mains close signal will be initiated and the mains will be paralleled with the bus. Once the mains has synchronized to the bus, the power will be ramped off the bus.

# Mains Open Operation: Press mains Open Button



- If mains switch didn't close, then mains open relay activates. 1)
- If mains switch already closed, first of all, the controller will transfer load to bus, and only then mains open relay activate.

### **Manual Stop Operation:**

- button; a LED besides the button will illuminate to Stop mode is selected by pressing the confirm the operation:
- a) If mains switch didn't close, then bus open relay activate.
- b) If mains switch already closed, first of all, the controller will transfer load to mains, and only then bus open relay activate.
- 2) The controller will issue a stop command and the genset is in "At Rest" mode.
- Any available 9560 in auto mode will be issued with a stop signal. Please refer to the 9510 operating 3) manual for further details of the stop sequence.



#### 5 MULTIPLE MAINS OPERATION

In a multiple mains system, the gensets are controlled by more than one 9560 mains controller and used to provide power to multiple loads.

Should one or more of the mains supplies fail, the generators are started and supply power to the load. If more than one mains supply has failed, the loads are transferred to the generators one by one.

If one mains supply returns, the 9560 connected to that mains supply will synchronies the generators with the mains and affect a no-break changeover. The generators continue to supply power to the remaining loads.

If more than one mains supply returns at the same time, then the 9560 with the highest priority will take control of the generators and affect a no-break changeover back to the mains supply.

HGM9560 priority fall into two types: status priority and module priority.

If status priorities are different, then the HGM9560 priority is up to the status priorities;

If status priorities are same, then the HGM9560 priority is up to the module priority;

The module priority can be set while the status priority can not.

### **Table 6 Status Priority**

Priority	Condition			
Highest	Auto mode, mains failed, bus not on load			
	Auto mode, mains has returned			
	Auto mode, mains failed, bus on load			
	Auto mode, mains available, requesting control over generators			
	Manual mode, sets running or about to run (start button has been pressed)			
	Auto mode, mains available			
<b>V</b>	Manual mode, sets not running			
Lowest Stop mode				



### 6 PROTECTIONS

### 6.1 WARNING ALARMS

Warnings are not shutdown alarms and do not affect the operation of the gen-set. Warning alarms does not lead to shutdown. Warning alarms types are as follows:

**Table 7 Warning Alarms** 

No	Туре	Description			
1	Battery Over Volt	When the controller detects that the battery voltage has exceeded the			
'	Dattery Over Voit	pre-set value, it will initiate a warning alarm.			
2	Battery Under Volt	When the controller detects that the battery voltage has fallen below the			
	Battery officer voic	pre-set value, it will initiate a warning alarm.			
3	Bus Breaker Fail	When the controller detects that the Bus Breaker Fail is not configured in			
	Das Breaker Fair	the input port, it will initiate a warning alarm.			
4	   Mains Breaker Fail	When the controller detects that the Mains Breaker Fail is not configured in			
	Wallo Breaker Fall	the input port, it will initiate a warning alarm.			
5	Digital Input	When the digit input port is set as User Configured and the action select			
	Digital input	"Warn", it will initiate a warning alarm.			
6	Fail to sync	When the controller does not detect synchronization signal within the			
	T dir to oyno	pre-set synchronization time, it will initiate a warning alarm.			
7	Min Sets Not Reached	When the controller detects fewer modules on the MSC link than the			
	Will Octo Not Nedolica	minimum number configured in the unit, it will initiate a warning alarm.			
8	Maintenance Due	When count down time is 0 and the action select "Warn", it will initiate a			
	Wantenance Duc	warning alarm.			
9	Insufficient Capacity	When the controller detects that the bus power percentage has exceeded			
		100%, and the action select "Warn", it will initiate a warning alarm.			
10	Output Mains Power	When the controller detects that the mains power has exceeded the pre-set			
	Limit	value, and the action selects "Warn", it will initiate a warning alarm.			
11	Mains Over Current 1	When the current of any phase of mains is over than the over current 1			
	manio over ourrent i	pre-set value, and the action selects" Warn", it will initiate a warning signal.			
12	Mains Over Current 2	When the current of any phase of mains is over than the over current 2			
'-	Manio Over Guitent Z	pre-set value, and the action selects" Warn", it will initiate a warning signal.			



### 6.2 TRIP AND STOP ALARMS

When the controller detects trip and stop signal, it immediately disconnects generator breaker, which leads to unloading and then generator is cooling down and stopped.

**Table 8 Trip and Stop Alarms** 

No	Туре	Description
1	Digital Input	When the digit input port is set as User Configured and the action select
'	Digital Inpat	"Trip and Stop", it will initiate a trip and stop alarm.
2	Mains Over Frequency	When the controller detects that the mains frequency has exceeded the
	ividino over i requerioy	pre-set value, it will initiate a trip and stop alarm.
3	Mains Under Frequency	When the controller detects that the mains frequency has fallen below the
3	ividing officer requency	pre-set value, it will initiate a trip and stop alarm.
4	Mains Over Voltage	When the controller detects that the mains voltage has exceeded the
7	Wallis Over Voltage	pre-set value, it will initiate a trip and stop alarm.
5	Mains Under Voltage	When the controller detects that the mains voltage has fallen below the
3	Wallis Officer Voltage	pre-set value, it will initiate a trip and stop alarm.
6	Mains ROCOF	When the controller detects that the rate of change of frequency has
0		exceeded the pre-set value, it will initiate a trip and stop alarm.
7	Mains Vector Shift	When the controller detects that the mains vector shift has exceeded the
/	Ividins vector sinit	pre-set value, it will initiate a trip and stop alarm.
8	Maintenance Due	When count down time is 0 and the action select "Trip and Stop", it will
0	Maintenance Due	initiate a trip and stop alarm.
		When the controller detects that the bus power percentage has exceeded
9	Insufficient Capacity	100%, and the action select "Trip and Stop", it will initiate a trip and stop
		alarm.
10	MSC Too Few Sets	When the controller detects fewer modules on the MSC link than the
10	I IVISC 100 Few Sets	minimum number configured in the unit, it will initiate a trip and stop alarm.



### 6.3 TRIP ALARM

On initiation of the trip condition the controller will de-energize the 'Close Generator' Output without stop the generator.

**Table 9 Trip Alarms** 

No.	Туре	Description		
1	Digital Input	When the digit input port is set as user configured and the action select		
<u>'</u>	Digital iliput	"Trip", it will initiate a trip alarm.		
2	Fail to ayna	When the controller does not detect synchronization signal within the		
	Fail to sync	pre-set synchronization time, it will initiate a trip alarm.		
3	Bus Breaker Fail	When the controller detects that the Bus Breaker Fail is not configured in		
3	Bus Breaker Fall	the input port, it will initiate a trip alarm.		
4	Maina Progler Fail	When the controller detects that the Mains Breaker Fail is not configured in		
4	Mains Breaker Fail	the input port, it will initiate a trip alarm.		
5	Inquifficient Consoity	When the controller detects that the bus power percentage has exceeded		
5	Insufficient Capacity	100%, and the action select "Trip", it will initiate a trip alarm.		

### **6.4 MAINS TRIP ALARM**

When controller detects the signal of mains trip, it will realize the output of mains open.

**Table 10 Mains Trip** 

No.	Туре	Description
1	Mains Trip of Input Port	When digital input port selection is user defined and the configuration is mains trip, the controller will initiate a signal of mains trip after the input port is active.
2	Output Mains Power Limit	When the controller detects that the mains power has exceeded the pre-set value, and the action select "Trip and Stop", it will initiate a trip and stop alarm.
3	Mains Over Current 1 Trip	When the current of any phase of mains is over than the over current 1 pre-set value, and the action selects" Mains Trip", it will initiate a tripping signal.
4	Mains Over Current 2 Trip	When the current of any phase of mains is over than the over current 2 pre-set value, and the action selects" Mains Trip", it will initiate a tripping signal.



### 7 WIRING CONNECTION

HGM9560 controller's rear as following:

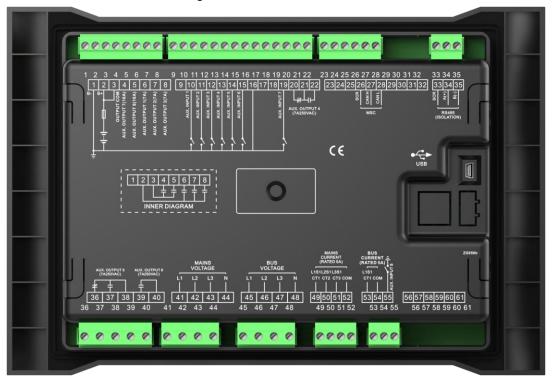


Fig.2 Controller Back Panel

**Table 11 Description of Terminal Connection** 

NO.	Functions	Cable Size	Remark		
1	DC input B-	2.5mm <sup>2</sup>	Connected with negative of starter battery.		
2	DC input B+	2.5mm <sup>2</sup>	Connected with positive of starter battery. If wire length is over 30m, better to double wires in parallel. Max. 20A fuse is recommended.		
3	COM Output 7,8	2.5mm <sup>2</sup>	Connected with B+.		
4	Aux. output 7	1.5mm <sup>2</sup>	B+ is supplied by 3 point, rated 1	16A.	
5	Aux. output 8	1.5mm <sup>2</sup>	B+ is supplied by 3 point, rated 1	16A.	
6	Aux. output 1	1.5mm <sup>2</sup>	B+ is supplied by 2 point, rated 7A.		
7	Aux. output 2	1.5mm <sup>2</sup>	B+ is supplied by 2 point, rated 7A.	Details see form 2.	
8	Aux. output 3	1.5mm <sup>2</sup>	B+ is supplied by 2 point, rated 7A.		
9	Reserved	/	This is reserved terminals, do no	ot connect to wire.	
10	Aux. input 1	1.0mm <sup>2</sup>	Ground connected is active (B-)		
11	Aux. input 2	1.0mm <sup>2</sup>	Ground connected is active (B-)	Details see form 3.	
12	Aux. input 3	1.0mm <sup>2</sup>	Ground connected is active (B-)		

NO.	Functions	Cable Size	Remark		
13	Aux. input 4	1.0mm <sup>2</sup>	Ground connected is active (B-)		
14	Aux. input 5	1.0mm <sup>2</sup>	Ground connected is active (B-)		
15	Aux. input 6	1.0mm <sup>2</sup>	Ground connected is active (B-)		
16-18	Reserved	/	This is reserved terminals, do not connect to wire.		
19	Aux. input 7	1.0mm <sup>2</sup>	Ground connected is active (B-) Details see form 3.		
20			Normally close outputs, rated 7A.		
21	Aux. output 4	1.5mm <sup>2</sup>	Public points of relay Details see form 2.		
22			Normally open outputs, rated 7A.		
23-25	Reserved	/	This is reserved terminals, do not connect to wire.		
26	MSC CAN	/	Impedance 1200, chielding wire in recommended its		
27	MSC CAN H	0.5mm <sup>2</sup>	Impedance- $120\Omega$ shielding wire is recommended, its single-end earthed.		
28	MSC CAN L	0.5mm <sup>2</sup>	Single-end earthed.		
33	RS485	/	lunnadamas 1000 akialdina viina ia vaaamanaad ita		
34	RS485+	0.5mm <sup>2</sup>	Impedance-120Ω shielding wire is recommended, its		
35	RS485-	0.5mm <sup>2</sup>	single-end earthed.		
36		2.5mm <sup>2</sup>	Normally close outputs, rated 7A.		
37	Aux. output 5	2.5mm <sup>2</sup>	Normally open outputs, rated 7A.		
38		2.5mm <sup>2</sup>	Public points of relay  Details see form 2.		
39	Aux. output 6	2.5mm <sup>2</sup>	Normally open outputs, rated 7A.		
40		2.5mm <sup>2</sup>	Public points of relay		
41	Mains A-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to A-phase of mains (2A fuse is recommended).		
42	Mains B-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to B-phase of mains (2A fuse is recommended).		
43	Mains C-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to C-phase of mains (2A fuse is recommended).		
44	Mains N-wire input	1.0mm <sup>2</sup>	Connected to N-wire of mains.		
45	Genset A-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to A-phase of genset (2A fuse is recommended).		
46	Genset B-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to B-phase of genset (2A fuse is recommended).		
47	Genset C-phase voltage sensing input	1.0mm <sup>2</sup>	Connected to C-phase of genset (2A fuse is recommended).		
48	Genset N-wire input	1.0mm <sup>2</sup>	Connected to N-wire of genset.		
49	Mains CT A-phase sensing	1.5mm <sup>2</sup>	Externally connected to secondary coil of current		

NO.	Functions	Cable Size	Remark		
	input		transformer (rated 5A).		
50	Mains CT B-phase sensing input	1.5mm <sup>2</sup>	Externally connected to secondary coil of current transformer (rated 5A).		
51	Mains CT C-phase sensing input	1.5mm <sup>2</sup>	Externally connected to secondary coil of current transformer (rated 5A).		
52	Mains CT COM	1.5mm <sup>2</sup>	See following section entitled Installation.		
53	1.5mm <sup>2</sup>		Externally connected to secondary coil of Bus CT		
54	Bus Current 1.5mm <sup>2</sup>		A-phase (rated 5A).		
55	Aux. input 8	1.0mm <sup>2</sup>	Ground connected is active (B-) Details see form 3.		



**NOTE**: USB ports in controller rear panel are configurable parameter ports, user can directly program controller via PC.



### 8 SCOPES AND DEFINITIONS OF PROGRAMMABLE PARAMETERS

### 8.1 CONTENTS AND SCOPES OF PARAMETERS

**Table 12 Contents and Scopes of Parameters** 

No.	Items	Parameters	Defaults	Description		
Mains	Mains Setting Setting					
Mains	Mains Setting-Basic					
1	AC System	(0~3)	0	0: 3P4W; 1: 3P3W; 2: 2P3W; 3: 1P2W.		
2	Rated Voltage	(30~30000)V	230	Standard for checking mains over/under voltage. (It is primary voltage when using voltage transformer; it is line voltage when AC system is 3P3W while it is phase voltage when using other AC system).		
3	Rated Frequency	(10.0~75.0)Hz	50.0	Standard for checking mains over/under frequency.		
4	Normal Time	(0~3000)s	10	The delay from mains abnormal to normal.		
5	Abnormal Time	(0~3000)s	5	The delay from mains normal to abnormal.		
6	Volt. Trans.(PT)	(0~1)	0	0: Disable; 1: Enable Primary volt. and secondary volt. can be set.		
7	Over Voltage	(0~200)%	120%	Setting value is mains rated voltage's percentage, and return value (default: 116%) and delay value (default: 5s) can be set.		
8	Under Voltage	(0~200)%	80%	Setting value is mains rated voltage's percentage, and return value (default: 84%) and delay value (default: 5s) can be set.		
9	Over Frequency	(0~200)%	114%	Setting value is mains rated frequency's percentage, return value (default: 110%) and delay value (default: 5s) can be set.		
10	Under Frequency	(0~200)%	90%	Setting value is mains rated frequency's percentage, return value (default: 94%) and delay value (default: 5s) can be set.		
11	Current Trans.	(5-12000)/5	500	The ratio of external CT		
12	Mains Rated (kW)	(1-60000)kW	345	Mains' active power, used for load distributes.		
13	Mains Rated (kVar)	(1-60000)kVar	258	Mains' reactive power, used for load distributes.		
14	Output Power Limit Alarm (PC)	(0-200)%	85%	When the controller detects that the mains power has exceeded the pre-set value, the		
15	Output Power Limit Action (PC)	(0-2)	0	corresponding alarm according to preset will be initiated. Action Type 0: Warn 1: Mains Trip 2: No Action		
16	Mains Over Current 1 (PC)	(0-2)	0	Action Type 0: Warn 1: Mains Trip 2: No Action		
	(1 0)	(0-12000)	500	Setting value.		

No.	Items	Parameters	Defaults	Description	
110.	recino	(0-12000)	480	Return value.	
		(0.0-3600.0)	30.0	Delay value.	
		(0-2)	0	Action Type 0: Warn 1: Mains Trip 2: No Action	
17	Mains Over Current 2	(0-12000)	600	Setting value.	
	(PC)	(0-12000)	580	Return value.	
		(0.0-3600.0)	1.0	Delay value.	
Main	s Split Setting (PC)	<u>-</u>	_		
1	Alarm Action	(0-1)	0	0: Trip and Stop; 1: Auxiliary mains fail If Auxiliary Mains Fail is selected, when alarm occurs, mains breaker will open and warning alarm will be initiated.	
2	Over Voltage	(0-200)%	105%	Setting value is mains rated voltage's	
3	Under Voltage	(0-200)%	95%	percentage, action (default: trip and stop) and delay value (default: 0.1s) can be set.	
4	Over Frequency	(0-200)%	105%	Setting value is mains rated frequency's	
5	Under Frequency	(0-200)%	95%	percentage, action (default: trip and stop) and delay value (default: 0.1s) can be set.	
6	ROCOF	(0-1.00)Hz/s	0.20	Setting value is rate of change of frequency (ROCOF), action (default: trip and stop) and delay value (default: 0.1s) can be set.	
7	Vector Shift	(0-20.0)°	6.0	Setting value is the change value of voltage waveform, action (default: trip and stop) and delay value (default: 0.1s) can be set.	
Time	r Setting				
1	Start Delay	(0~3600)s	5	Time from mains abnormal or remote start signal is active to start genset.	
2	Stop Delay	(0~3600)s	30	Time from mains normal or remote start signal is inactive to stop genset.	
Batte	ry Setting				
1	Rated Voltage	(0-60.0)V	24.0	Standard for checking battery over/under voltage.	
2	Over Voltage	(0-200)%	120%	Setting value is mains rated voltage's percentage, return value (default: 115%) and delay value (default: 60s) can be set.	
3	Under Voltage	(0-200)%	85%	Setting value is mains rated voltage's percentage, return value (default: 90%) and delay value (default: 60s) can be set.	
Bus Setting					
1	AC System	(0~3)	0	0: 3P4W; 1: 3P3W; 2: 2P3W; 3: 1P2W.	
2	Rated Voltage	(30~30000)V	230	To offer standards for detecting of bus' over/under voltage. (It is primary voltage when using voltage transformer; it is line voltage when AC system is 3P3W while it is phase voltage when using other AC system).	

No.	Items	Parameters	Defaults	Description
3	Rated Frequency	(10.0~600.0) Hz	50.0	To offer standards for detecting of over/under frequency.
4	Volt. Trans.(PT)	(0~1)	0	0: Disable; 1:Enable The primary secondary voltages can be set.
5	Bus Rated (kW)	(1~20000)kW	276	Bus' active power, used for load distributes.
6	Bus Rated (kVar)	(1~20000)kvar	210	Bus' reactive power, used for load distributes.
7	Load Ramp Rate	(0.1~100.0)%	3.0	Speed rate(%/s) of genset upload/unload
8	Load Ramp Point	(0.1~40.0)%	10.0	Each "Load Ramp Point" unit value increases,
9	Load Ramp Delay	(0~30)s	0	the load will added after "Load Ramp Delay".
10	Load CT Enable	(0~1)	0	0: Disable; 1:Enable
11	Load CT	(5~12000)/5	500	The ratio of external CT.
12	Insufficient Capacity Delay (PC)	(0~1800)s	20	When the controller detects that the bus power percentage has exceeded 100%, after
13	Insufficient Capacity Action (PC)	(0~2)	0	the "Insufficient Capacity Delay", it will initiate a corresponding alarm according to the preset value.  Action: 0: Warn 1: Trip 2: Trip and Stop
Switc	h Setting			
1	Close Time	(0~20.0)s	5.0	Pulse width of switch on. When it is 0, means output constantly.
2	Open Time	(0~20.0)s	3.0	Pulse width of switch off.
3	Mains Failure Trip (PC)	(0~1)	0	0: Disable; 1:Enable
4	Stop Mode MB Control	(0~1)	1	0: Disable; 1:Enable
Switc	h Input Port Setting			
Input	Port 1		T	
1	Function Selection	(0~55)	31	Remote start (demand). See Table 14.
2	Active Type	(0~1)	0	0: Closed to active 1: Open to active
	Port 2		T	T
1	Function Selection	(0~55)	0	User defined. See Table 14.
2	Active Type	(0~1)	0	0: Closed to active 1: Open to active
3	Arming	(0~2)	2	0: From paralleling 1: Always 2:Never
4	Active Actions	(0~4)	3	0: Warn; 1:Trip and stop 2:Trip 3: Indication 4: Mains Trip.
5	Active Delay	(0~20.0)s	2.0	Time from detecting active to confirm
6	Description			LCD display detailed contents when the input is active.
Input	Port 3			
1	Function Selection	(0~55)	0	User defined. See Table 14.
2	Active Type	(0~1)	0	0: Closed to active 1: Open to active
3	Arming	(0~2)	2	0: From paralleling 1: Always 2:Never

No.	Items	Parameters	Defaults	Description		
4	Active Actions	(0~4)	3	0: Warn; 1:Trip and stop 2:Trip		
4	Active Actions	(0.94)	3	3: Indication 4: Mains Trip.		
5	Active Delay	(0~20.0)s	2.0	Time from detecting active to confirm		
6	Description			LCD display detailed contents when the input		
	·			is active.		
•	Port 4	\(\(\alpha\)	1	I		
1	Function Selection	(0~55)	13	Bus Closed. See Table 14.		
2	Active Type	(0~1)	0	0: Closed to active		
Innut	Port 5			1: Open to active		
1 1	Function Selection	(0~55)	0	User defined. See form 3		
ı	Function Selection	(0~33)	0	0: Closed to active		
2	Active Type	(0~1)	0	1: Open to active		
3	Arming	(0~2)	2	0: From paralleling 1: Always 2:Never		
-	Airming			0: Warn; 1:Trip and stop 2:Trip		
4	Active Actions	(0~4)	3	3: Indication 4: Mains Trip.		
5	Active Delay	(0~20.0)s	2.0	Time from detecting active to confirm		
		(		LCD display detailed contents when the input		
6	Description			is active.		
Input	Port 6	1				
1	Function Selection	(0~55)	0	User defined. See Table 14.		
2	Active Type	(0, 1)	0	0: Closed to active		
2	Active Type	(0~1)	0	1: Open to active		
3	Arming	(0~2)	2	0: From paralleling 1: Always 2:Never		
4	Active Actions	(0~4)	3	0: Warn; 1:Trip and stop 2:Trip		
	7 totive 7 totions	, ,		3: Indication 4: Mains Trip.		
5	Active Delay	(0~20.0)s	2.0	Time from detecting active to confirm		
6	Description			LCD display detailed contents when the input		
Input Port 7			is active.			
		(0.55)		III 16 1 0 TH 14		
1	Function Selection	(0~55)	0	User defined. See Table 14.  0: Closed to active		
2	Active Type	(0~1)	0	1: Open to active		
				0: From paralleling		
3	Arming	(0~2)	2	1: Always 2: Never		
				0: Warn; 1:Trip and stop 2:Trip		
4	Active Actions	(0~4)	3	3: Indication 4: Mains Trip.		
5	Active Delay	(0~20.0)s	2.0	Time from detecting active to confirm		
		, ,		LCD display detailed contents when the input		
6	Description			is active.		
Input	Input Port 8					
1	Function Selection	(0~55)	15	Mains Closed. See Table 14.		
2	Active Type	(0~1)	0	0: Closed to active		
	2 Active Type (0~1) 0 1: Open to active					
Outp	ut Ports Setting					
	-					

No.	Items	Parameters	Defaults	Description	
_	ut Port 1				
1	Function Selection	(0~239)	44	Bus OK. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1: Normally close	
Outpu	ut Port 2				
1	Function Selection	(0~239)	48	Common Alarm. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1: Normally close	
Outpu	ut Port 3	<del>_</del>			
1	Function Selection	(0~239)	46	Mains OK. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; : Normally close	
Outpu	ut Port 4				
1	Function Selection	(0~239)	47	Synchronizing See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1: Normally close	
Outpu	ut Port 5				
1	Function Selection	(0~239)	31	Close Mains Output. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; : Normally close	
Outpu	ut Port 6				
1	Function Selection	(0~239)	29	Close Bus Output. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1: Normally close	
Outpu	ut Port 7				
1	Function Selection	(0~239)	32	Open Mains Output. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1:Normally close	
Outpu	ut Port 8	T	1		
1	Function Selection	(0~239)	30	Open Bus Output. See Table 13.	
2	Active Type	(0~1)	0	0: Normally open; 1: Normally close	
Modu	Module Setting				
1	Power On Mode	(0~2)	0	0: Stop mode 1: Manual mode 2: Auto mode	
2	Comm. Address	(1~254)	1	Controller's address during remote sensing.	
3	Language	(0~2)	0	0: Simplified Chinese 1: English 2: Others	
4	Password	(0~65535)	00318	For entering advanced parameters setting.	
5	Date & Time			Format: YYYY.mm.dd HH:MM:SS.	
6	Stop Bit	(0~1)	0	0: 2 stop bits; 1: 1 stop bit	
Sche	duled Run				
1	Enable Setting	(0~1)	0	0: Disable; 1: Enable	
2	Load Setting	(0~1)	0	0: Disable; 1: Enable	
3	Cycle Selection	(0-3)	0	0: Monthly 1: Weekly 2: Daily 4: Custom Weekly.	

No.	Items	Parameters	Defaults	Description
4	Start Time ( Week)	(0-6)	0	0~6 correspond to Sun.~Mon.
5	Start Time (Day)	(1~31)	1	1~31 correspond to 1st ~31st.
6	Start Time (Hour)	(0~23)	0	0~23 correspond to 0~23'o clock.
7	Start Time ( Minute)	(0~59)	0	0~59 correspond to 0~59 minutes.
8	Total Running Time	(0~30000)	30	Scheduled running time, unit: min.
0	Total Rulling Time	(0~30000)	30	1: Start Time (Day)1: Start Time (Hour)
				1: Start Time (Day) 1: Start Time (Hour)  1: Start Time (Minute)1: Total Running time
9	Custom Weekly	(0~6)	0	to 16: Start Time (Day)16: Start Time (Hour)
	Setting	, ,		16: Start Time (Minute)16: Total Running
				time
Sync	Setting -Basic		•	
1	MOOID	(0.01)	1	It is the ID mark of the MSC communication
1	MSC ID	(0-31)	1	internet. All the MSC ID should be unique.
2	MSC Priority	(0-31)	0	Smaller values represent higher priorities.
3	Sync Freq. Gain	(0-500)	20	Adjust and control before paralleling.
4	Sync Freq. Stability	(0-2000)	20	Adjust and control before paralleling.
5	Sync Volt. Gain	(0-500)	20	Adjust and control after paralleling.
6	Sync Volt. Stability	(0-2000)	20	Adjust and control after paralleling.
7	kW Control Gain	(0-500)	20	Adjust and control before paralleling.
8	kW Control Stability	(0-2000)	20	Adjust and control before paralleling.
9	kvar Control Gain	(0-500)	20	Adjust and control before paralleling.
10	kvar Control Stability	(0-2000)	20	Adjust and control before paralleling.
	•	,		It is considered Bus no power when Bus
11	Dead Bus Volt	(10-50)V	30	voltage is lower than dead Bus voltage.
		(0-1.00)Hz	0.10	Adjust bus frequency and enable it greater
	Slip Frequency			than mains frequency.
				When slip frequency is 0:
10				If the frequency difference is greater than
12				0.1Hz, then the frequency will be
				synchronized;
				If the frequency difference is smaller than
				0.1Hz, then the phase will be synchronized;
				The voltage difference between bus and
				mains. It is considered voltage
13	Voltage Difference	(0-30)V	3	synchronization when the voltage difference
				between mains and Bus is lower than
				synchronization voltage difference.
14	Positive Freq	(0-2.0)Hz	0.2	The frequency difference between bus and
	Difference	(3 2.0)112	J	mains. It is considered frequency
	Negative Freq	(0-2.0)Hz	0.1	synchronization when the frequency
15				difference between mains and Bus is less
	Difference			than Positive Freq Difference but more than
				Negative Freq Difference.
	Phase Angle	(0.00)		Initial phase difference between bus and
16	Difference	(0-20)°	10	mains. It is considered Check Phase Angle
				when the initial phase difference is lower

No.	Items	Parameters	Defaults	Description	
				than synchronization phase difference.	
17	Fail to Sync Delay	(5.0-300.0)s	60.0	When the controller detects no Sync signal	
18	Fail to Sync Action	(0-1)	0	during the preset delay, it will send corresponding alarm signal according to the action type.  Action Type:  0: Warn; 1: Trip.	
19	MSC Number	(1-32)	2		
20	Comm. Alarm Action	(0~2)	1	Action 0: None 1: Warn 2: Trip	
21	Comm. Ratio	(0~3)	1	0: 500KBit/s; 1: 250KBit/s; 2: 125KBit/s; 3: 50KBit/s.	
22	Scheduled Run PCT	(0-100)%	80	Schedule the load value of other genset when start on demand.	
23	Scheduled Stop PCT	(0-100)%	50	Schedule the load value of other genset when start on demand.	
24	Load Mode	(0-2)	0	0: Bus Control; 1: Mains Control; 2: Load Control.	
25	Output (kW)	(0-100.0)%	30.0	Used for load control.	
26	Output (kVar)	(0-100.0)%	8.0	Used for load control.	
27	Min Start Sets	(1-32)	1	When the controller does not detect the Min	
28	Not Reached Act	(0-2)	1	Start Sets during the preset delay, it will send	
29	Request Start Delay	(0-3600)s	120	corresponding alarm signal according to the action type. Action Type: 0: No Action; 1: Warn; 2: Trip.	
30	MSC Transformer	(0~1)	0	0: Disable; 1: Enable	
Sche	duled Not Run				
1	Enable Setting	(0~1)	0	0: Disable; 1: Enable	
2	Cycle Selection	(0~2)	0	0: Monthly 1: Weekly 2: Daily	
3	Not Start Time ( Week)	(0~6)	0	0~6 correspond to Sun.~Mon.	
4	Not Start Time ( Day)	(1~31)	1	1~31 correspond to 1 <sup>st</sup> ~31 <sup>st</sup> .	
5	Not Start Time ( Hour)	(0~23)	0	0~23 correspond to 0~23'o clock.	
6	Not Start Time ( Minute)	(0~59)	0	0~59 correspond to 0~59 minutes.	
7	Total Time	(0~30000)	30	Not scheduled running time, unit: min.	
Main	Maintenance Setting				
1	Enable Setting	(0~1)	0	0: Disable; 1: Enable	
2	Time Setting (PC)	(0~5000)	30	Maintenance time setting.	
3	Maintenance Time Due Action	(0~2)	0	0: Warn 1: Trip 2: Trip and stop	



### 8.2 ENABLE DEFINITION OF PROGRAMMABLE OUTPUT PORTS

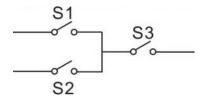
**Table 13 Definable Contents of Programmable Output Ports** 

No.	Туре	Description
0	Not Used	
1~6	Reserved	
7	Custom Combined 1	
8	Custom Combined 2	
9	Custom Combined 3	Details of formation description also as about full coning.
10	Custom Combined 4	Details of function description please see the following.
11	Custom Combined 5	
12	Custom Combined 6	
13~17	Reserved	
18	Audible Alarm	Action when warning, shutdown, trips. Can be connected annunciator externally. When "alarm mute" configurable input port is active, it can remove the alarm.
19~25	Reserved	
26	Remote Control Output	This port is controlled by communication (PC).
27~28	Reserved	
29	Close Bus Output	Control bus to take load.
30	Open Bus Output	Control bus to off load.
31	Close Mains Output	Control mains to take load.
32	Open Mains Output	Control mains to off load.
33~43	Reserved	
44	Bus OK	Action when bus is normal.
45	Reserved	
46	Mains OK	Action when mains is normal.
47	Synchronizing	Action when controller is synchronizing.
48	Common Alarm	Action when genset common warning, common shutdown, common trips alarm.
49	Common Trip and Stop	Action when common trip and stop alarm.
50	Common Shutdown	Action when common shutdown alarm.
51	Common Trip	Action when common trips alarm.
52	Common Warn	Action when common warning alarm.
53	Reserved	
54	Battery Over Voltage	Action when battery's over voltage warning alarm.
55	Battery Under Voltage	Action when battery's low voltage warning alarm.
56~68	Reserved	
69	Digital Input 1 Active	Action when input port 1 is active
70	Digital Input 2 Active	Action when input port 2 is active
71	Digital Input 3 Active	Action when input port 3 is active
72	Digital Input 4 Active	Action when input port 4 is active
73	Digital Input 5 Active	Action when input port 5 is active
74	Digital Input 6 Active	Action when input port 6 is active
75	Digital Input 7 Active	Action when input port 7 is active
76	Digital Input 8 Active	Action when input port 8 is active

No.	Туре	Description
77~124	Reserved	
125	Mains Inactive	
126	Mains Over Freq	
127	Mains Over Volt	
128	Mains Under Freq	
129	Mains Under Volt	
130	Phase Sequence Wrong	
131	Mains Loss of Phase	
132	Mains Freq. Change	
133	Mains Vector Offset	
134	Mains Over Current	
135~229	Reserved	
230	Stop Mode	Action in stop mode.
231	Manual Mode	Action in Manual mode.
232	Reserved	Reserved.
233	Auto Mode	Action in Auto mode.
234	Generator Load	
235	Mains Load	
236~239	Reserved	

#### 8.2.1 DEFINED COMBINATION OUTPUT

Defined combination output is composed by 3 parts, condition output S1 or S2 and condition output S3.



S1 or S2 is TRUE, while S3 is TRUE, Defined combination output is outputting;

S1 and S2 are FALSE, or S3 is FALSE, Defined combination output is not outputting.

**ANOTE:** S1, S2, S3 can be set as any contents except for "defined combination output" in the output setting.

**NOTE:** 3 parts of defined combination output (S1, S2, S3) couldn't include or recursively include themselves.

Example,

Contents of probably condition output S1: output port 1 is active;

Close when probably condition output S1 is active /inactive: close when active (disconnect when inactive);

Contents of probably condition output S2, output port 2 is active;

Close when probably condition output S2 is active /inactive: close when active (disconnect when inactive);

Contents of probably condition output S3: output port 3 is active;

Close when probably condition output S3 is active /inactive: close when active (disconnect when inactive);

When input port 1 active or input port 2 active, if input port 3 is active, Defined combination output is outputting;

If input port 3 inactive, Defined combination output is not outputting;

When input port 1 inactive and input port 2 inactive, whatever input port 3 is active or not, Defined combination output is not outputting.

### 8.3 DEFINED CONTENTS OF DIGITAL INPUT PORTS (ALL ACTIVE WHEN CONNECT TO GROUND (B~))

**Table 14 Definable Contents of Digital Input Ports** 

No.	Туре	Description
0	Users Configured	Including following functions, Indication: indicate only, not warning or shutdown. Warning: warn only, not shutdown. Trip and stop: alarm, generator unloads and shutdown after hi-speed cooling Trip: alarm, generator unloads but not shutdown. Mains Trip: alarm, mains opening outputs. Never: input inactive. Always: input is active all the time. From paralleling: detect when the genset is parallel running.
1	Mains Switch Control Unavailable	The status of mains switch is judged by mains status. If mains power is normal, the switch status is closed; while if mains power is abnormal, the switch status is open.
2	Alarm Mute	Can prohibit "Audible Alarm" output when input is active.
3	Reset Alarm	Can reset shutdown alarm and trip alarm when input is active.
4	Reserved	
5	Lamp Test	All LED indicators are illuminating when input is active.
6	Panel Lock	All buttons in panel is inactive except and there is in the right of first row in LCD when input is active.
7~8	Reserved	there is   In the right of hist fow in LCD when input is active.
9	Inhibit Auto Stop	In <b>Auto</b> mode, during generator normal running, when input is active, prohibit generator shutdown automatically.
10	Inhibit Auto Start	In <b>Auto</b> mode, prohibit generator start automatically when input is active.
11	Inhibit Scheduled Start	In <b>Auto</b> mode, prohibit fixed timing start genset when input is active.
12	Mains Switch Control Unavailable Feedback	The status of mains switch is judged by mains status and mains closed status. If mains power is normal and mains closed status is active; the switch status is closed; otherwise, the switch status is open.
13	Aux Bus Closed	Connect bus loading switch's Aux. Point.
14	Inhibit Bus Load	Prohibit bus switch on when input is active.
15	Aux Mains Closed	Connect mains loading switch's Aux. Point.
16	Inhibit Mains Load	Prohibit mains switch on when input is active.
17	Auto Mode Lock	When input is active, controller enters into Auto mode; all the keys except keys except are inactive.
18	Auto Mode Invalid	When input is active, controller won't work under Auto mode.

No.	Туре	Description
		key and simulate auto key input does not work.
19	Reserved	
20	Reserved	
21	Inhibit Alarm Stop	All shutdown alarms are prohibited except emergence stop.(Means battle mode)
22	Aux Instrument Mode	All outputs are prohibited in this mode.
23	Reserved	
24	Reset Maintenance	Controller will set maintenance time and date as default when input is active.
25~27	Reserved	
28	Remote Start (On Load)	In <b>Auto</b> mode, when the input is active, genset can be started and with load after genset is OK; when the input is inactive, genset will stop automatically.
29	Remote Start (Off Load)	In <b>Auto</b> mode, when the input is active, genset can be started and without load after genset is OK; when the input is inactive, genset will stop automatically.
30	Aux. Manual Start	In <b>Auto</b> mode, when the input is active, genset will start automatically; when the input is inactive, genset will stop automatically
31	Remote Start (On Demand)	In <b>Auto</b> mode, when the input is active, all genset that need to be parallel will start according to the priority and calling other generator according to the load.
32	Remote Start (Island)	In <b>Auto</b> mode, when the input is active, genset will start automatically; genset will take load when it is normal running while mains off load. when the input is inactive, mains will take load while genset off load and stop automatically.
33	Simulate Stop key	An external button (not self-locking) can be connected and
34	Simulate Manual key	pressed as simulate panel.
35	Reserved	
36	Simulate Auto key	
37	Simulate Start key	An external button (not self-locking) can be connected and
38	Simulate B-Load key	pressed as simulate panel.
39	Simulate M-Load key	
40	10s Detecting Mains	When input is active, detecting mains normal or abnormal delay changes to 10s.
41~44	Reserved	
45	Simulate Mains Normal	In <b>Auto</b> mode, when the input is active, mains is normal.
46	Simulate Mains Abnormal	In <b>Auto</b> mode, when the input is active, mains is abnormal.
47	Alternative Config 1	Hoore oon oot different neverneters to realize it seem to relie
48	Alternative Config 2	Users can set different parameters to make it easy to select
49	Alternative Config 3	current configuration via input port.
50	Reserved	
51	Speed-up Input	Load mode selection is Bus Control mode. When input port is active, the active power of generation side is increased.
52	Speed-down Input	Load mode selection is Bus Control mode. When input port is

No.	Туре	Description
		active, the active power of generation side is decreased.
53	Step-up Output	Load mode selection is Bus Control mode. When input port is active, the reactive power of generation side is increased.
54	Step-down Output	Load mode selection is Bus Control mode. When input port is active, the reactive power of generation side is decreased.
55	Reserved	

### 9 PARAMETERS SETTING

**ACAUTION:** Please change the controller parameters when generator is in standby mode only (e. g. configurable input, configurable output, various delay), otherwise, alarming to stop and other abnormal conditions may happen.

**NOTE**: Maximum set value must over minimum set value in case that the condition of too high as well as too low will happen.

NOTE: When setting the warning alarm, please set the correct return value; otherwise, maybe there is abnormal alarm. When setting the maximum value, the return value must less than setting; when setting the minimum value, the return value must over setting.

**NOTE:** Configurable input could not be set as same items; otherwise, there are abnormal functions. However, the configurable output can be set as same items.



#### 10 COMMISSIONING

- 1) Start the genset, perform on-load test and then stop the genset respectively.
- 2) Close the genset switch, parallel the genset to Bus and then open the genset switch respectively.
- 3) Set each genset (e.g. HGM9510) as auto mode.
- 4) Set the HGM9560 controller as manual mode, when the mains is normal, perform mains switch close/open test and check if the mains switch is normal; then open the mains switch if it is ok.
- 5) Start the HGM9560 controller manually, when the bus is normal, perform bus switch close/open test and check if the bus switch is normal; then open the bus switch if it is ok.
- 6) Press the mains close button, the bus will anti-synchronize to mains; then mains close after the synchronization is successful and parallel running is beginning.
- 7) Perform on-load test and load transfer test.
- 8) Set the HGM9560 controller as manual mode, the controller will control the genset to start/stop and share load automatically according to the preset condition.



### 11 MAINS PARALLEL

### 11.1 BUS CONTROL MODE

Output preset active power, reactive power and power factor.

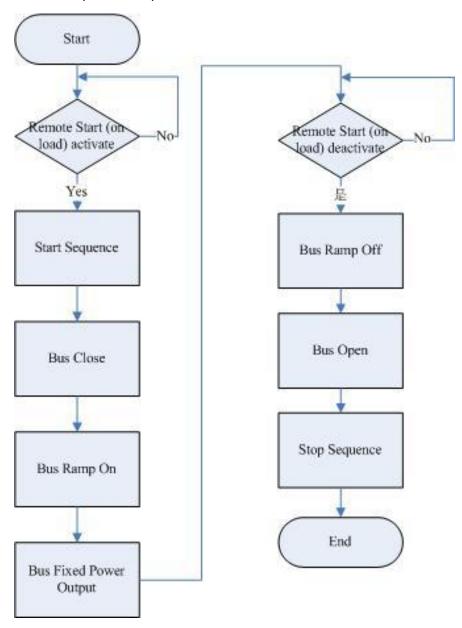


Fig.3 Bus Control Mode



#### 11.2 MAINS CONTROL MODE

If the power value is set as a positive number, when the mains input increases above the power setpoint, the generator bus will supply the extra load in order to maintain the mains input at the predefined level (mains peak lopping mode).

If the power value is set as a negative number, the generator bus will supply the preset power to mains. The total output power of the generator bus is the sum of the consumption power and the preset power which supplied by generator bus to mains.

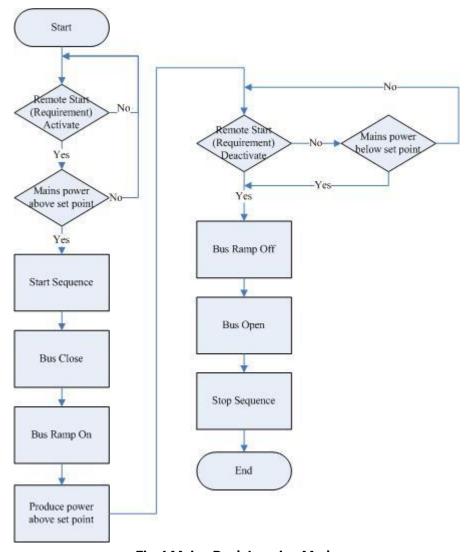


Fig.4 Mains Peak Lopping Mode



### 11.3 LOAD TAKEOVER MODE

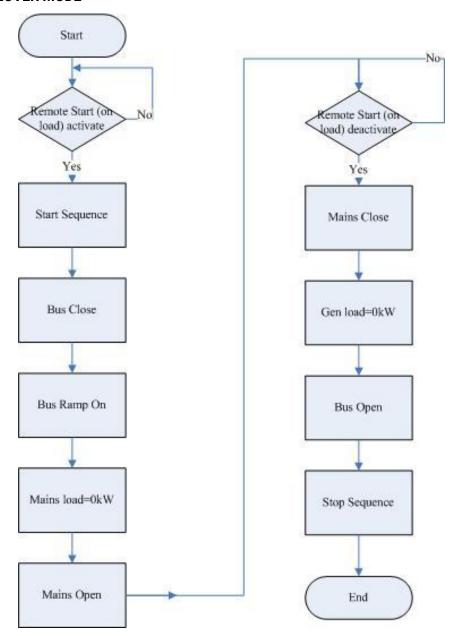


Fig.5 Load Takeover Mode



### 11.4 AMF MODE

Automatic mains failure mode. No-break return to mains supply.

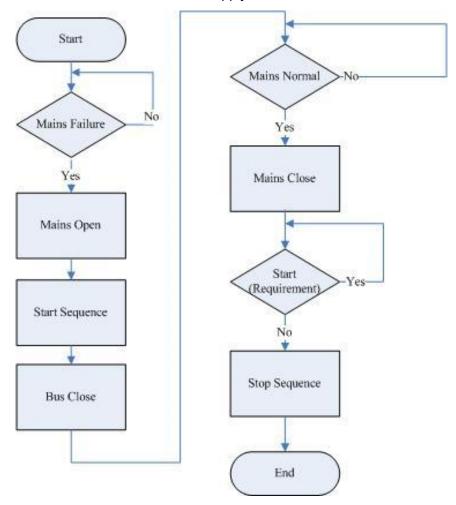


Fig.6 AMF Mode



### 11.5 ISLAND MODE

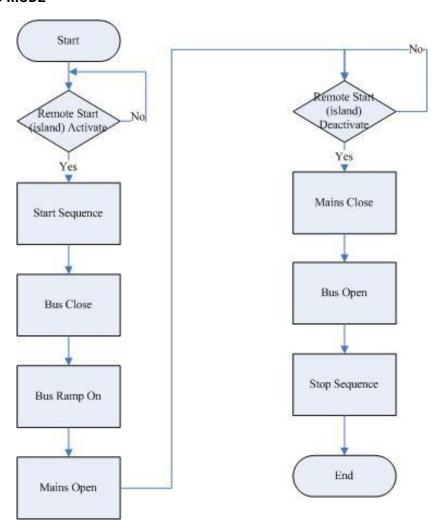


Fig.7 Island Mode



### 12 TYPICAL APPLICATION

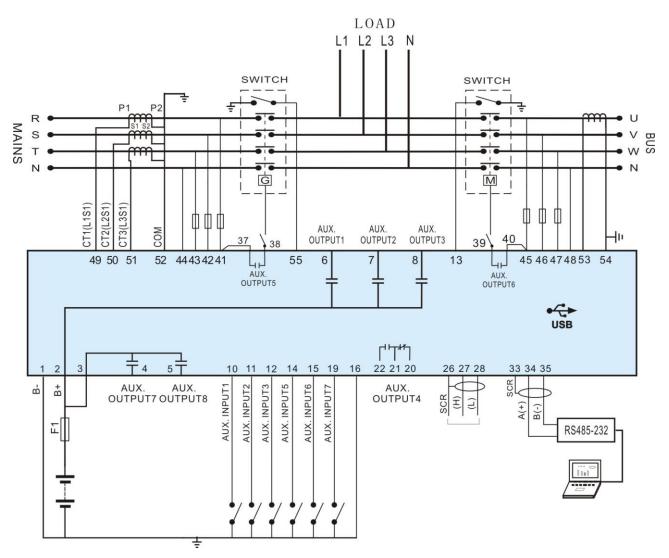
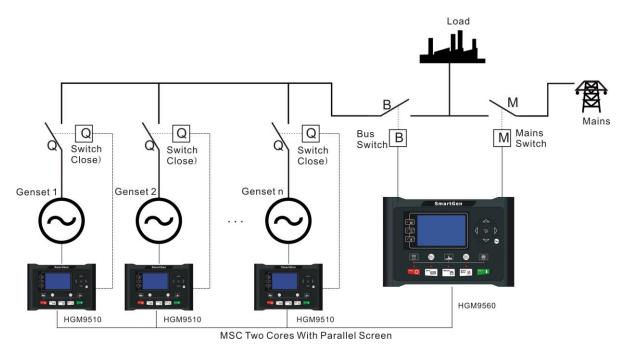


Fig.8 HGM9560 Typical Diagram



### 13 TYPICAL APPLICATION



**Fig.9 Single Set Communication** 

Note: Bus CT is a non-issue for single set communication and the bus power can be obtained from MSC communication; therefore, the users can disable it.

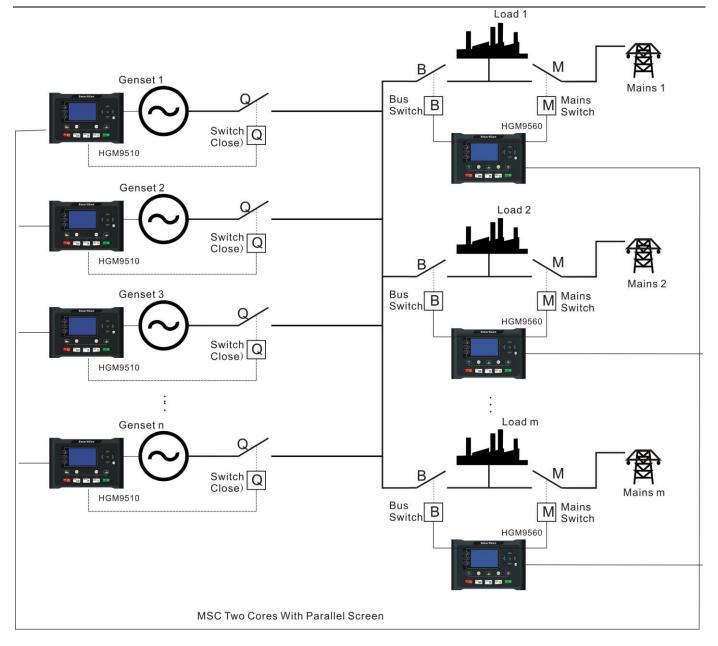


Fig.10 Multi Set Communication

**A**Note: Bus CT is important for multi set communication, so make sure that it is soundly connected.



#### 14 INSTALLATION

Controller is panel built-in design; it is fixed by clips when installed. The controller's overall dimensions and cutout dimensions for panel, please refers to as following:

Unit: mm

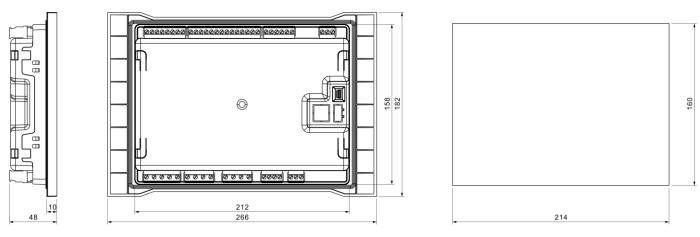


Fig.11 Case Dimensions and Panel Cutout

### 1) Battery Voltage Input

NOTE: HGM9560 controller can suit for widely range of battery voltage DC(8~35)V. Negative of battery must be connected with the engine shell. The diameter of wire which from power supply to battery must be over 2.5mm<sup>2</sup>. If floating charge configured, please firstly connect output wires of charger to battery's positive and negative directly, then, connect wires from battery's positive and negative input ports in order to prevent charge disturbing the controller's normal working.

### 2) Output And Expand Relays

**CAUTION:** All outputs of controller are relay contact output type. If need to expand the relays, please add freewheel diode to both ends of expand relay's coils (when coils of relay has DC current) or, add resistance-capacitance return circuit (when coils of relay has AC current), in order to prevent disturbance to controller or others equipment.

### 3) AC Input

Current input of HGM9560 controller must be connected to outside current transformer. And the current transformer's secondary side current must be 5A. At the same time, the phases of current transformer and input voltage must correct. Otherwise, the current of collecting and active power maybe not correct.

**NOTE**: ICOM port must be connected to negative pole of battery.

WARNING! When there is load current, transformer's secondary side prohibit open circuit.

### 4) Withstand Voltage Test

**ACAUTION!** When controller had been installed in control panel, if need the high voltage test, please disconnect controller's all terminal connections, in order to prevent high voltage into controller and damage it.

### 15 USB

Users can set the controller's parameters and monitor the controller's status via the test software which provided by Smartgen company. The connection way between PC and controller as following:



Fig.12 USB Connection



### 16 FAULT FINDING

### **Table 15 Fault Finding**

Symptoms	Possible Solutions	
	Check starting batteries;	
Controller no response with power.	Check controller connection wirings;	
	Check DC fuse.	
	Check related switch and its connections according to the information	
Shutdown Alarm in running	on LCD;	
	Check programmable inputs.	
Genset running while ATS not	Check ATS;	
transfer	Check the connections between ATS and controllers.	
	Check connections;	
	Check setting of COM port is correct or not;	
RS485 communication is abnormal	Check RS485's connections of A and B is reverse connect or not;	
	Check RS485 transfer module whether damage or not;	
	Check communication port of PC whether damage.	